# Efficient Mitigation of Error Floors in Quantum Error Correction using Non-Binary LDPC Code

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### Background

- Recent studies<sup>1</sup> have reported that binary CSS codes based on  $\mathbb{F}_q$ -valued LDPC codes<sup>2</sup> exhibit near-hashing-bound decoding performance over the depolarizing channel using joint BP decoding.
- However, for codes with a low coding rate R,
  a significant error floor has been observed.
- This study aims to mitigate or eliminate the error floor—ideally achieving a target frame error rate (FER) of  $10^{-4}$  near the hashing bound.

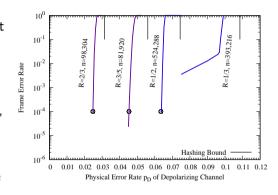


Figure: Joint BP performance of QEC with non-binary LDPC codes with  $\mathbb{F}_q$   $(q=2^8)$ .

<sup>&</sup>lt;sup>1</sup>Komoto and Kasai, **under minor revision**, *npj Quantum Information*, 2025.

<sup>&</sup>lt;sup>2</sup>Kasai, Hagiwara, Imai and Sakaniwa, IEEE Trans. Information Theory, 2011.

#### Code Construction

- We employ orthogonal  $\mathbb{F}_q$ -valued parity-check matrices  $H_X$  and  $H_Z$  with column weight two and girth 12.
- The matrices  $H_X$  and  $H_Z$  are constructed to be orthogonal by leveraging the structure of circulant permutation matrices or affine permutation matrices
- ullet By using companion matrices, the matrices  $H_X$  and  $H_Z$  can also be regarded as binary parity-check matrices.

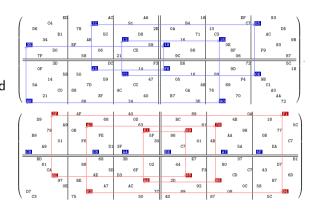


Figure: Parity-check matrics  $H_Z$  and  $H_X$  over  $\mathbb{F}_q$  (q=256).

#### Joint BP decoding

- Joint BP decoding is a belief propagation algorithm that simultaneously estimates <u>x</u> and <u>z</u>.
- Joint BP decoding begins by measuring the syndromes  $\underline{s}$  and  $\underline{t}$  corresponding to the noise vectors  $\underline{x}$  and  $\underline{z}$ .

$$\underline{s} = H_Z \underline{x}$$
 and  $\underline{t} = H_X \underline{z}$ .

• Joint BP iteratively estimates  $\hat{\underline{x}}^{(\ell)}$  and  $\hat{\underline{z}}^{(\ell)}$  at each iteration  $\ell$ .

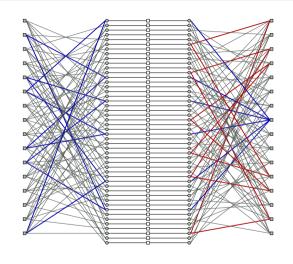


Figure: Factor graph of joint BP.

### Insights into Decoding Failures in the Error Floor Regime

- In the error floor regime, joint BP decoding is sufficient to correctly estimate the noise in most cases. However, it occasionally fails to do so.
- In such failure cases, the joint BP algorithm becomes trapped in a union of length-12 cycles on the Tanner graph.
- In our experiments, decoding failures in the error floor regime caused by combined cycles involving both the X- and Z-side factor graphs were not observed.

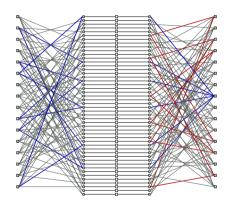


Figure: Factor graph of joint BP.

## Overview of Proposed Decoding Algorithm

- 1. First, we run joint belief propagation for a sufficiently large number of iterations. In most cases, this step alone is enough to correctly estimate the noise.
- However, if joint BP decoding fails—typically due to being trapped in cycles of length 12
   —we then proceed to estimate the trapping cycles.
- 3. Once the trapping cycles are identified, we estimate the remaining undetermined noise by solving a linear system of equations.

#### Method: Estimation of Trapping Cycles

 At each iteration, we keep track of the locations where the estimated noise and the syndrome values have recently changed:

 $K_d^{(\ell)}$  : Estimated noise that have changed within the past d iterations

 $I_d^{(\ell)}$  : Syndromes of the estimated noise that have changed within the past d iterations

- For sufficiently large  $\ell$  and d, it was observed that  $K_d^{(\ell)}$  and  $I_d^{(\ell)}$  tend to cover the columns and rows of trapping cycles, respectively.
- This observation enables us to efficiently identify the trapping cycles.

|        | Estimation for $\underline{x}$ |                  |                               |                  | Estimation for $z$            |                  |                             |                  |
|--------|--------------------------------|------------------|-------------------------------|------------------|-------------------------------|------------------|-----------------------------|------------------|
| $\ell$ | $ K_{err}^{(\ell)} $           | $ K_d^{(\ell)} $ | $ I_{\mathrm{err}}^{(\ell)} $ | $ I_d^{(\ell)} $ | $ K_{\mathrm{err}}^{(\ell)} $ | $ K_d^{(\ell)} $ | $ I_{\text{err}}^{(\ell)} $ | $ I_d^{(\ell)} $ |
| 0      | 14944                          | 0                | 9689                          | 9689             | 15017                         | 0                | 9741                        | 9741             |
| 1      | 13731                          | 4270             | 8618                          | 10371            | 13845                         | 4165             | 8677                        | 10399            |
| 2      | 12875                          | 6986             | 7676                          | 10631            | 12959                         | 6864             | 7791                        | 10656            |
| 3      | 12108                          | 8776             | 7036                          | 10757            | 12306                         | 8660             | 7178                        | 10791            |
| 4      | 11693                          | 10053            | 6558                          | 10852            | 11765                         | 10017            | 6717                        | 10883            |
| 5      | 11297                          | 11035            | 6221                          | 10907            | 11370                         | 11022            | 6304                        | 10941            |
| 6      | 10866                          | 11808            | 5862                          | 10951            | 11043                         | 11808            | 6028                        | 10986            |
| 7      | 10542                          | 12446            | 5640                          | 10974            | 10667                         | 12518            | 5745                        | 11027            |
| 8      | 10300                          | 12950            | 5464                          | 10044            | 10364                         | 13119            | 5537                        | 10141            |
| 9      | 10069                          | 11536            | 5216                          | 9337             | 10099                         | 11796            | 5334                        | 9442             |
|        |                                |                  |                               |                  |                               |                  |                             |                  |
| - :    | :                              |                  | :                             | ;                |                               | :                | - :                         | :                |
| 41     | 466                            | 5682             | 462                           | 3625             | 846                           | 5956             | 684                         | 3755             |
| 42     | 221                            | 5088             | 204                           | 3167             | 473                           | 5405             | 436                         | 3421             |
| 43     | 90                             | 4337             | 103                           | 2742             | 227                           | 4822             | 225                         | 3053             |
| 44     | 15                             | 3633             | 25                            | 2307             | 81                            | 4243             | 95                          | 2664             |
| 45     | 2                              | 2980             | 2                             | 1856             | 21                            | 3575             | 27                          | 2210             |
| 46     | 3                              | 2257             | 4                             | 1389             | 5                             | 2882             | 7                           | 1755             |
| 47     | 2                              | 1595             | 2                             | 909              | 0                             | 2197             | 0                           | 1300             |
| 48     | 2                              | 973              | 2                             | 565              | 0                             | 1538             | 0                           | 897              |
| 49     | 3                              | 538              | 4                             | 261              | 0                             | 998              | 0                           | 531              |
| 50     | 2                              | 250              | 2                             | 118              | 0                             | 542              | 0                           | 264              |
| 51     | 2                              | 101              | 2                             | 29               | 0                             | 256              | 0                           | 108              |
| 52     | 3                              | 19               | 4                             | 6                | 0                             | 87               | 0                           | 30               |
| 53     | 2                              | 6                | 2                             | 6                | 0                             | 23               | 0                           | 7                |
| 54     | 2                              | 6                | 2                             | 6                | 0                             | 5                | 0                           | 0                |
| 55     | 3                              | 6                | 4                             | 6                | 0                             | 0                | 0                           | 0                |
| 56     | 2                              | 6                | 2                             | 6                | 0                             | 0                | 0                           | 0                |
| 57     | 2 3                            | 6                | 2                             | 6                | 0                             | 0                | 0                           | 0                |
| 58     | 3                              | 6                | 4                             | 6                | 0                             | 0                | 0                           | 0                |
| :      | :                              | :                | ;                             | :                | :                             | ;                | :                           | :                |

Figure: Transition of the joint BP decoding state over iterations (d=8).

## Method: Post-Processing Algorithm

• For estimating X-noise, solve a linear system involving the syndrome  $\underline{s}$  and the noise vector  $\underline{x}_K$  associated with the trapping cycles. This is done using a submatrix of  $H_Z$  restricted to the set of column positions K corresponding to the trapping cycles:

$$\underline{s} = (H_Z)_K \underline{x}_K + (H_Z)_{\overline{K}} \underline{\hat{x}}_{\overline{K}}$$

The size of K is independent of the code length, and the system can be solved by Gaussian elimination with computational complexity  $O(|K|^3)$ .

- ullet Similarly, estimate the Z-noise vector by solving the corresponding linear system.
- Error correction is regarded as successful if and only if

$$\underline{x} + \hat{\underline{x}} \in C_X^{\perp}$$
 and  $\underline{z} + \hat{\underline{z}} \in C_Z^{\perp}$ .

#### Results

- The error floor was mitigated to some extent.
- A relatively high error floor still remained.
- The remaining error floor is attributed to the presence of length-12 cycles that contain non-zero codewords in

$$C_Z \setminus C_X^{\perp}$$
 and  $C_X \setminus C_Z^{\perp}$ .

These codewords lead to logical errors in the decoding process.

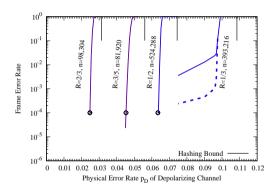


Figure: Comparison: joint BP (solid) with joint BP+post-processin (dashed)

### Recent Result: Code Construction to Avoid Small Logical Errors<sup>3</sup>

- In binary codes, any cycle with column weight 2 always contains a nonzero codeword.
   However, this is not necessarily the case in the non-binary setting.
- By ensuring that the determinant of each cycle is nonzero, we can eliminate nonzero codewords from the cycles.
- We modified the  $\mathbb{F}_q$ -valued entries in the length-12 cycles so that the corresponding codewords are necessarily the **zero codeword**.
- As a result, the error floor disappeared at least down to FER =  $10^{-4}$ .

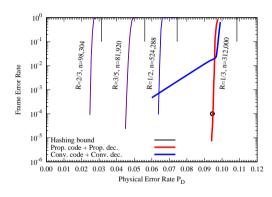


Figure: Comparison: Conventional method (blue) with proposed method (red).

<sup>&</sup>lt;sup>3</sup>K. Kasai, "Quantum error correction exploiting degeneracy to approach the hashing bound," arXiv:2506.15636, 2025.

#### Conclusions and Future work

- We successfully constructed binary CSS codes that scale well across a wide range of coding rate, achieving FER  $=10^{-4}$  by using non-binary LDPC codes.
- To further approach the hashing bound, we aim to incorporate techniques originally developed for classical codes, including:
  - Spatial Coupling
  - Multiplicative Repetition
  - Generalized LDPC Codes
- Currently, no upper bound on the girth of cycles leading to logical errors is known. This may open the possibility for applying density evolution analysis in future work.
- If you have ideas related to these directions, I would be very happy to hear them.

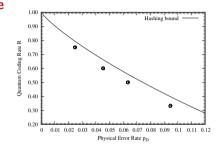


Figure: Physical Error Rate required for FER= $10^{-4}$  vs. Coding Rate